Pinhole Camera Visualisations of Accretion Disks around Kerr Black Holes

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David Kling Pinhole Cam Visualisations of Accretion Disks around Kerr BH

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Einstein equations and equations of motion

The Einstein equations

The metric tensor is determined by the Einstein equations:

$$G^{\mu}{}_{\nu} + g^{\mu}{}_{\nu}\Lambda = 8\pi T^{\mu}{}_{\nu} .$$
 (1)

In vacuum on small scales they reduce to

$$R^{\mu}{}_{\nu} = 0$$
 . (2)

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Einstein equations and equations of motion

Schwarzschild and Kerr spacetime

Axisymmetric stationary Kerr spacetime:

$$ds^{2} = -\left(1 - \frac{2Mr}{\Sigma^{2}}\right) dt^{2} - \frac{4Mar}{\Sigma^{2}} \sin^{2}\theta \, dt \, d\phi + \frac{\Sigma^{2}}{\Delta} \, dr^{2} + \Sigma^{2} \, d\theta^{2} + \frac{A}{\Sigma^{2}} \sin^{2}\theta \, d\phi^{2} , \qquad (3)$$

where

$$\Sigma^2 = r^2 + a^2 \cos^2 \theta , \qquad (4)$$

$$\Delta = r^2 - 2Mr + a^2 , \qquad (5)$$

$$A = \left(r^2 + a^2\right)^2 - a^2 \Delta \sin^2 \theta \ . \tag{6}$$

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Einstein equations and equations of motion

Horizons

[Bardeen 1972, Visser 2008, Younsi 2013]:

- red: static limit (r₀)
- dark-blue: outer event horizon (r₊)
- green: inner event horizon (r_)
- turquoise: inner static limit (r
 _)
- only physical singularity at:

$$\Sigma^2\coloneqq r^2+a^2\cos^2 heta=0$$
 .



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Einstein equations and equations of motion

Geodesic equations in Boyer-Lindquist coordinates

Using $2L = g_{\mu\nu} \dot{x}^{\mu} \dot{x}^{\nu}$ (Lagrangian of a freely falling test particle) one obtains the following equations for geodesics in Kerr spacetime [Younsi 2013]:

$$\dot{t} = E + \frac{2Mr}{\Sigma^2 \Delta} \left[\left(r^2 + a^2 \right) E - a l_z \right] , \qquad (7)$$

$$\dot{r}^2 = \frac{\Delta}{\Sigma^2} \left(\mu + E\dot{t} - I_z \dot{\phi} - \Sigma^2 \dot{\theta}^2 \right) , \qquad (8)$$

$$\dot{\theta}^2 = \frac{1}{\Sigma^4} \left[Q + \left(E^2 + \mu \right) a^2 \cos^2 \theta - l_z^2 \cot^2 \theta \right] , \qquad (9)$$

$$\dot{\phi} = \frac{2aMrE + \left(\Sigma^2 - 2Mr\right)I_z\csc^2\theta}{\Sigma^2\Delta} .$$
(10)

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Einstein equations and equations of motion

Geodesic equations in Boyer-Lindquist coordinates

- Move to second derivatives of r and θ to avoid the squares. \Rightarrow 6 coupled differential equations $(\dot{t}, \dot{r}, \ddot{r}, \dot{\phi}, \dot{\theta}, \ddot{\theta})$.
- Solved by fourth order Runge-Kutta with fifth order Runge-Kutta error precision control.

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Tetrads Defining the pinhole camera Defining the accretion disk

Image-plane method vs. pinhole camera method



Tetrads Defining the pinhole camera Defining the accretion disk

Pinhole camera method



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Tetrads Defining the pinhole camera Defining the accretion disk

What are tetrads?

A tetrad is a set of orthonormal basis vectors [Misner et al. 1973]

$$\underline{\underline{e}}_{(\hat{\mu})} \cdot \underline{\underline{e}}_{(\hat{\nu})} = \eta_{\hat{\mu}\hat{\nu}} . \tag{11}$$

Counter-example: Basis vectors in Boyer-Lindquist coordinates are neither normalised, nor orthogonal to each other:

$$\underline{e}_{(\mu)} \cdot \underline{e}_{(\nu)} = g_{\alpha\beta} \underline{e}^{\alpha}_{(\mu)} \underline{e}^{\beta}_{(\nu)} = g_{\alpha\beta} \delta_{\mu}{}^{\alpha} \delta_{\nu}{}^{\beta} = g_{\mu\nu} .$$
(12)

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Constructing a stationary observer's tetrad

Define the pinhole camera's four-velocity as

$$\underline{e}_{(\hat{t})} := (u^{\mu}) = \begin{pmatrix} u^t(x^{\mu}) \\ \vec{o} \end{pmatrix} = e^t_{(\hat{t})} \underline{e}^t_{(t)} , \qquad (13)$$

where it was used that $e_{(\hat{t})}^t = u^t$ [Misner et al. 1973]. This yields:

$$-1 \stackrel{!}{=} \underline{e}_{(\hat{t})} \cdot \underline{e}_{(\hat{t})} = \left(e_{(\hat{t})}^{t}\right)^{2} \underline{e}_{(t)} \underline{e}_{(t)}$$
(14)



Tetrads Defining the pinhole camera Defining the accretion disk

Constructing a stationary observer's tetrad

Similarly suitable $\hat{\theta}$ and \hat{r} vectors are obtained:

$$\underline{\underline{e}}_{(\hat{r})} = \frac{1}{\sqrt{g_{rr}}} \underline{\underline{e}}_{(r)} = \frac{\sqrt{\Delta}}{\Sigma} \underline{\underline{e}}_{(r)} , \qquad (16)$$
$$\underline{\underline{e}}_{(\hat{\theta})} = \frac{1}{\sqrt{g_{\theta\theta}}} \underline{\underline{e}}_{(\theta)} = \frac{1}{\Sigma} \underline{\underline{e}}_{(\theta)} . \qquad (17)$$

The ansatz for the ϕ -basis vector must respect the off-diagonal terms of the Kerr metric in BL coordinates:

$$\underline{\underline{e}}_{(\hat{\phi})} = K\left(x^{i}\right)\underline{\underline{e}}_{(\phi)} + P\left(x^{i}\right)\underline{\underline{e}}_{(t)} .$$
(18)

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Constructing a stationary observer's tetrad

The orthonormality conditions give two equations, which are used to determine K and P. This finally yields:

$$\underline{e}_{(\hat{\phi})} = \frac{\sqrt{-g_{tt}}}{\sqrt{\Delta}\sin\theta} \left(\underline{e}_{(\phi)} - \frac{g_{\phi t}}{g_{tt}}\underline{e}_{(t)}\right) . \tag{19}$$

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Initialising the four-momenta

Pinhole camera method by Bohn et al. (2014):

$$\xi^{\mu} = C \ e^{\mu}_{(\hat{t})} - e^{\mu}_{(\hat{r})} - \frac{\beta}{r_0} \ e^{\mu}_{(\hat{\theta})} - \frac{\alpha}{r_0} \ e^{\mu}_{(\hat{\phi})}$$
(20)

- C normalisation constant, which is determined by $\underline{p} \cdot \underline{p} = \mu$ ($\mu = 0$ for photons and $\mu = -1$ for massive particles).
- r₀ causes that the pinhole camera zooms in on the accretion disk.
- α, β are spaced equidistant in the interval [-22M, 22M].

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Angular velocity profile

- assume fast rotating disk, trajectories of emitters approximated by circular motion [cf. Shakura and Sunyaev 1973]
- inner edge of disk at ISCO: $r_{\text{inner}} = r_{\text{ISCO}}$; outer edge: $r_{\text{outer}} = 20M$.



Particles on circular orbits in the equatorial plane have an angular velocity of [Bardeen et al. 1972]

$$rac{{
m d}\phi}{{
m d}t}=\Omega_{
m K}=rac{\sqrt{M}}{a\sqrt{M}+r^{3/2}}$$
 . (21)

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Redshift

Define fluid's and observer's four-velocity:

$$\begin{pmatrix} u_{\text{fluid}}^{\mu} \end{pmatrix} = (u_{\text{fluid}}^{t}, 0, 0, u_{\text{fluid}}^{\phi})$$
$$= u_{\text{fluid}}^{t}(1, 0, 0, \Omega_{\mathcal{K}}) ,$$
(22)

$$(u_{\rm obs}^{\mu}) = (u_{\rm obs}^{t}, 0, 0, 0)$$
 (23)

Using ${\it E}_{
m fluid} = - {\it p}_lpha u^lpha_{
m fluid}$ one obtains:

$$g = 1 + z \coloneqq \frac{E_{\text{fluid}}}{E_{\text{obs}}} = \frac{\dot{t}_{\text{fluid}}}{\dot{t}_{\text{obs}}} \left(1 - \Omega_{\text{K}} \frac{l_z}{E}\right)$$
 (24)

[Courtesy of Dr. Younsi, who kindly gave me this derivation].

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General relativistic radiative transfer (GRRT) equations

• Computation of intensity by solution of the GRRT equations [Fuerst and Wu 2004, Baschek et al. 1997]:

$$\frac{\mathrm{d}\mathcal{I}}{\mathrm{d}\lambda} = -p_{\alpha}u^{\alpha}|_{\lambda}\left(-\alpha_{0,\nu}\mathcal{I} + \frac{j_{0,\nu}}{\nu_{0}^{3}}\right) \ . \tag{25}$$

Equivalent formulation [Younsi 2013]:

$$\frac{\mathrm{d}\tau_{\nu}}{\mathrm{d}\lambda} = g\alpha_{0,\nu} , \qquad (26)$$

$$\frac{\mathrm{d}\mathcal{I}}{\mathrm{d}\lambda} = g\left(\frac{j_{0,\nu}}{\nu_0^3}\right) \mathrm{e}^{-\tau_{\nu}} . \qquad (27)$$

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- Lorentz-invariant intensity [Rybicki and Lightman 2004, Younsi 2013]: $\mathcal{I} = I_{\nu}/\nu^3$; specific intensity: I_{ν}
- optical depth [Baschek et al. 1997, Younsi 2013]: $\tau_{\nu}(\lambda) = -\int_{\lambda_0}^{\lambda} \alpha_{0,\nu}(\lambda') p_{\alpha} u^{\alpha}|_{\lambda'} d\lambda',$ where α_{ν} is the absorption, defined by [Rybicki and Lightman 2004] $dI_{\nu} = -\alpha_{\nu}I_{\nu} ds,$ with the distance ds the beam travels
- assumed vanishing absorption outside the disk: $\alpha_{0,\nu} \stackrel{!}{=} 0$
- ansatz for the emissivity coefficient: $j_{0,\nu} \propto r^{-3}$.

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Tetrads Defining the pinhole camera Defining the accretion disk

Code structure



References

Intensity, redshift and coordinate patches Code validation Movies of different orbits

$\mathsf{Redshift} - (r, \theta) = (1000 \ M, 85^\circ)$

• left: a/M = 0, right: a/M = 0.998



1+z

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Higher order photons



Higher order photons can make several turns around the black hole.

This yields the characteristic photon rings.

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Intensity $-(r, \theta) = (1000 \ M, 85^{\circ})$

• left: a/M = 0, right: a/M = 0.998

References



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Inner most stable circular orbit (ISCO) [Bardeen 1972]



Green line for counterblue line for co-rotating (massive) particles.

In the Schwarzschild limit the ISCO for co-rotating particles coincides with the ISCO of counter-rotating ones.

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Rotation in θ – animation, a/M = 0.5



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Coordinate patches $-(r, \theta) = (1000M, 25^{\circ})$

References

• left: a/M = 0, right: a/M = 0.998



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Coordinate patches – $(r, \theta) = (1000M, 85^{\circ})$



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Coordinate patches – $(r, \theta) = (5M, 85^{\circ})$



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Up-spinning black hole



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Comparison of 1 + z – left: $r = 10^3 M$, right: $r = 10^6 M$

References

• $a/M = 0.998, \ \theta = 85^{\circ}$



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Hyperbolic Orbit – a/M = 0.5





- created a method that is able to visualise the radiation emanating from an accretion flow
- visualisation tool for curved spacetimes, basically applicable to any other spacetime
- provides visual description of the GR effects happening close to the horizon (using proper coordinates even below)

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Conclusion – future work

- using other disk models/accretion flows
- implement gravitational lensing of background
- reconstruction of pinhole camera with comoving tetrad
- reformulation of code in 3+1 decomposition of spacetime
- considering other spacetimes, e.g. binary black holes.

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Thank you for your attention!

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